

Your Home as Doctor: Smart Homes Enable Medical Diagnosis

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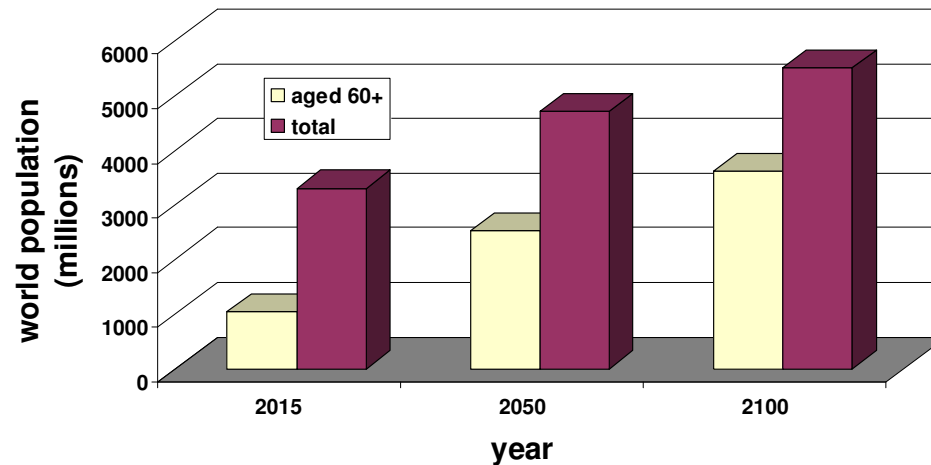


Outline

- **Motivation**
- **System Architecture**
- **Blocks' Design & Experimental Results**
- **System Design & Experimental Results**
- **Durability**
- **Conclusions**

Motivation

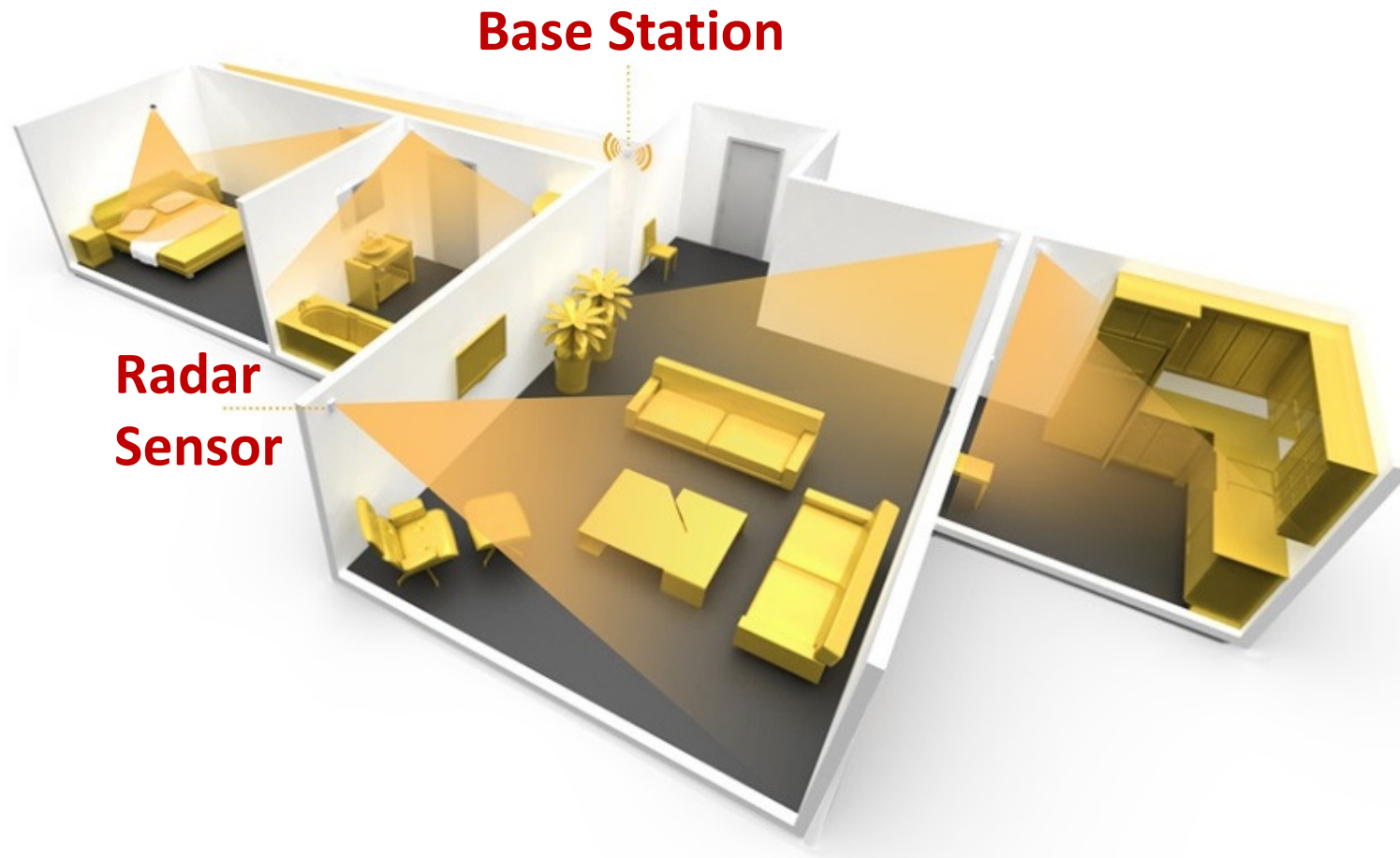
- **Observation: ageing population**



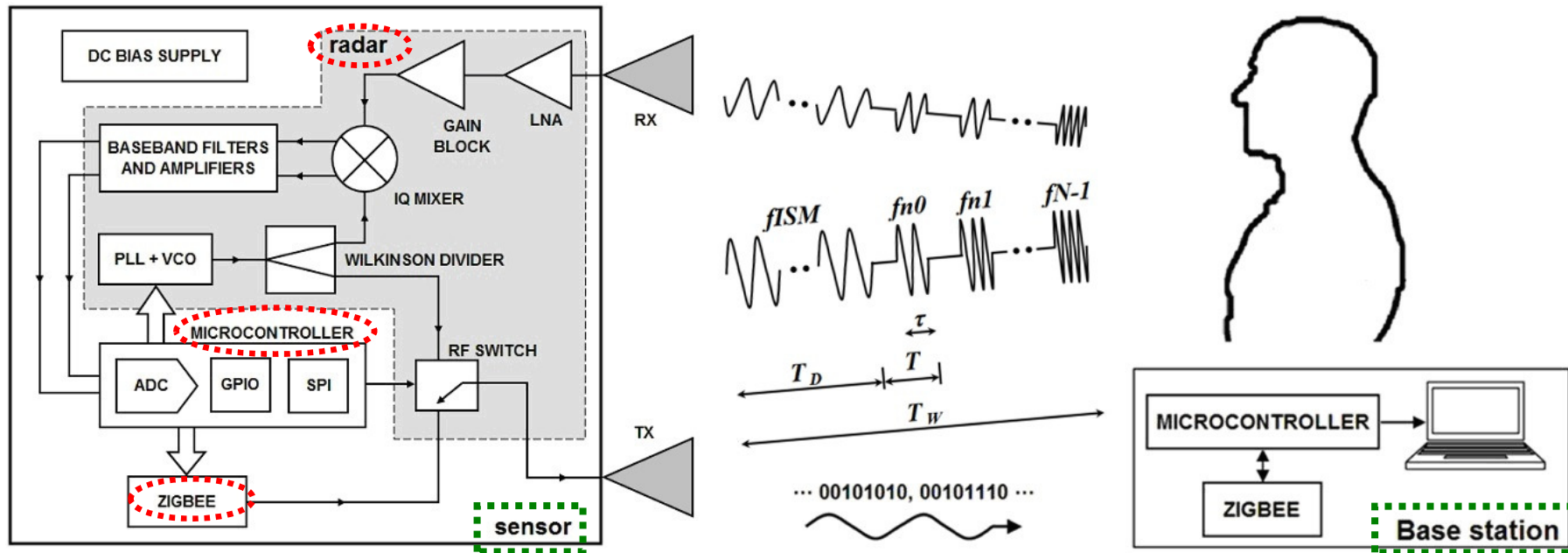
Source: bbc.com

- **Importance of Ambient Assisted Living**
= long-term health monitoring
- Fall detection
 - Localization
 - Vital signs monitoring

Approach: **Radar** WSN



WRSN System Architecture

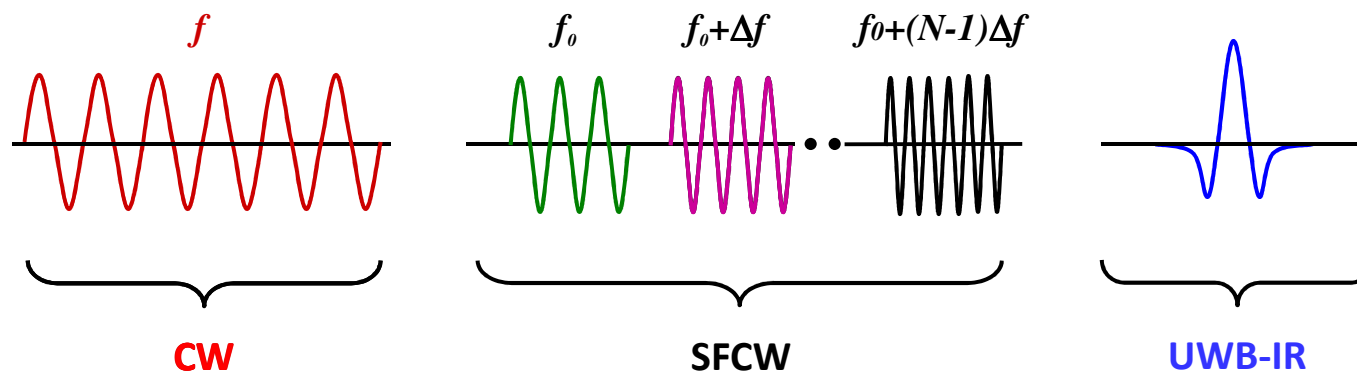


M. Mercuri, et al., "Analysis of an indoor biomedical radar-based system for health monitoring," *IEEE Trans. Microw. Theory Techn.*, vol. 61, no. 5, pp. 2061-2068, May 2013.



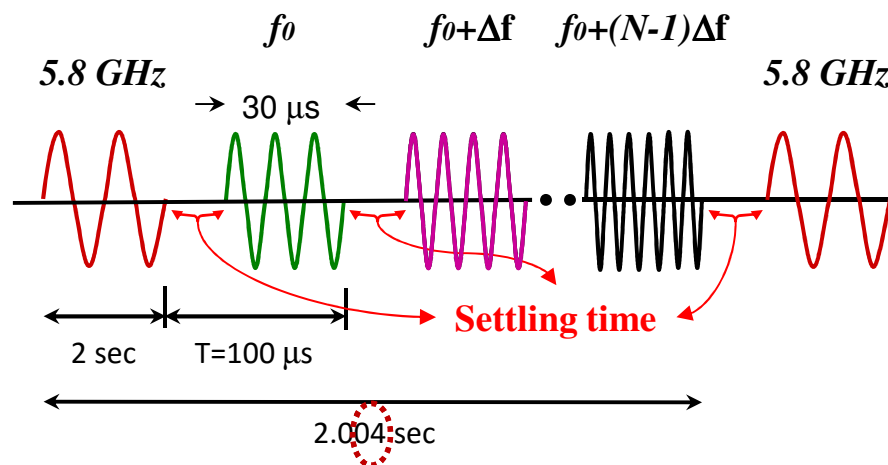
Radar Technologies

| type | frequency bandwidth | ranging meas. | Doppler | complexity (& costs) |
|---------------|------------------------|---------------|---------|----------------------|
| CW | narrowband | NO | YES | low |
| UWB IR | UWB | YES | NO | high |
| SFCW/ FMCW | UWB (& narrow band) | YES | YES | low-medium |



Radar Waveform

- ***fISM*** → fall detection
→ vital signs monitoring



- **SFCW waveform** → localization

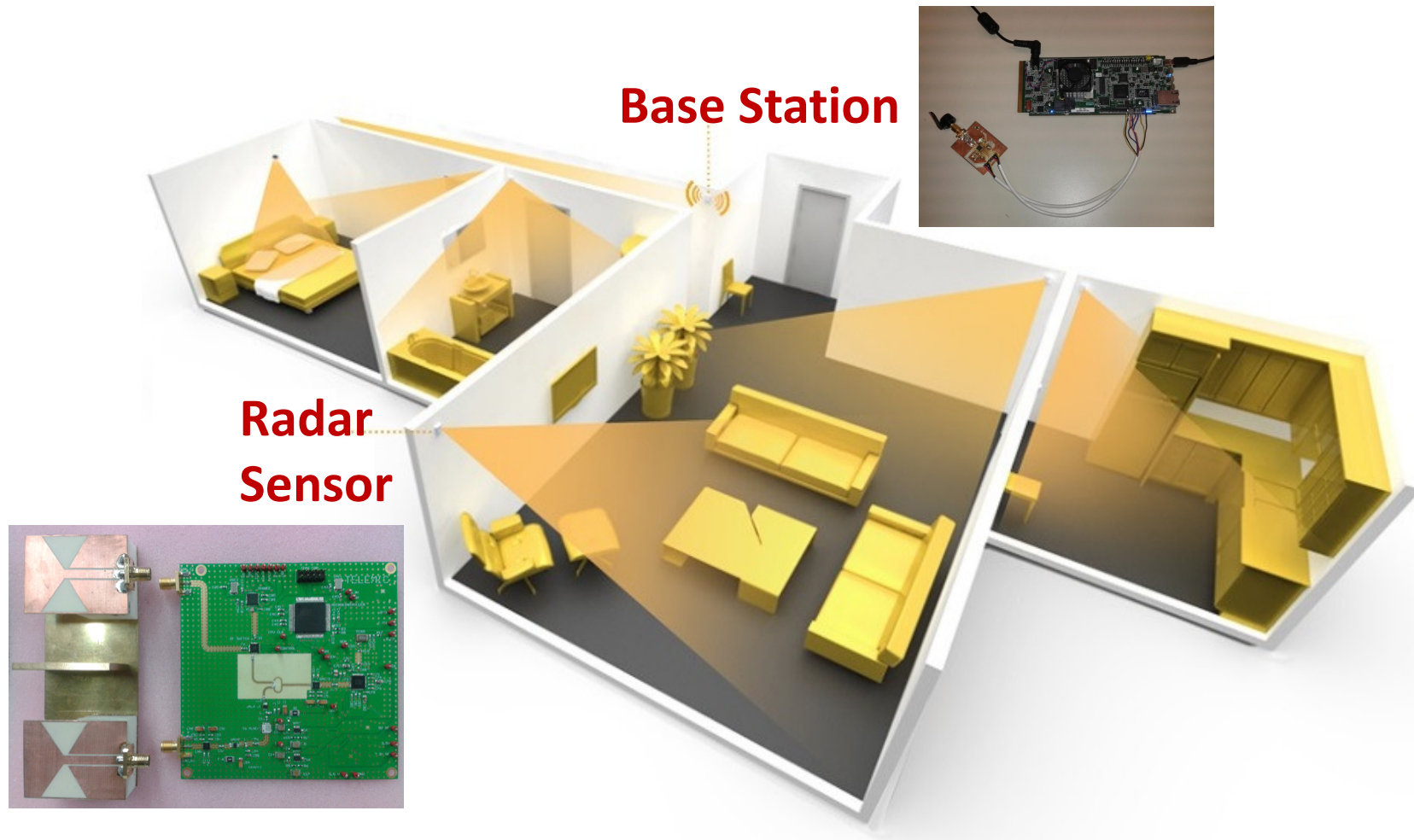
$$\left\{ \begin{array}{l} f_0 = 6 \text{ GHz} \\ N = 40 \\ \Delta f = 25 \text{ MHz} \\ R_{MAX} = 6 \text{ m} \\ \Delta R = 15 \text{ cm} \end{array} \right.$$



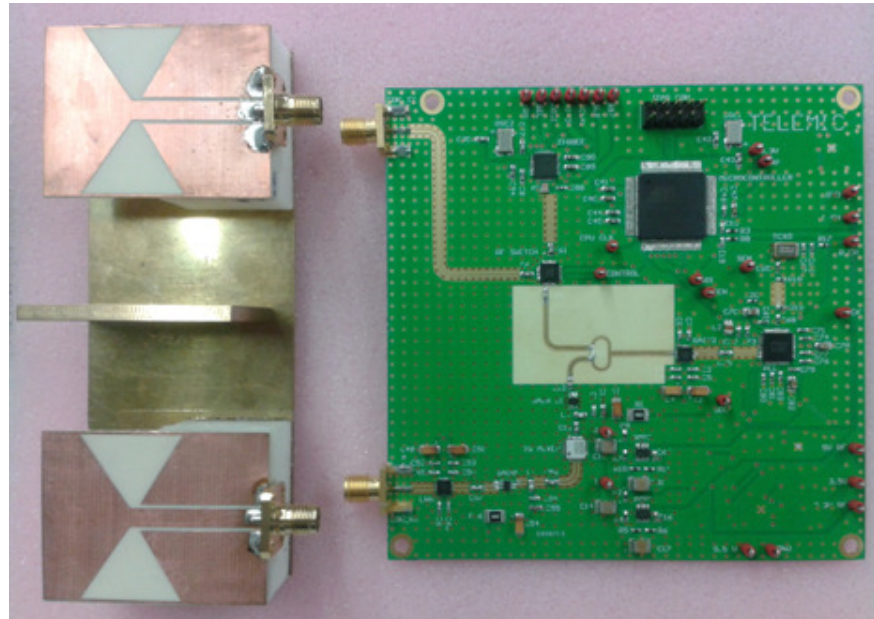
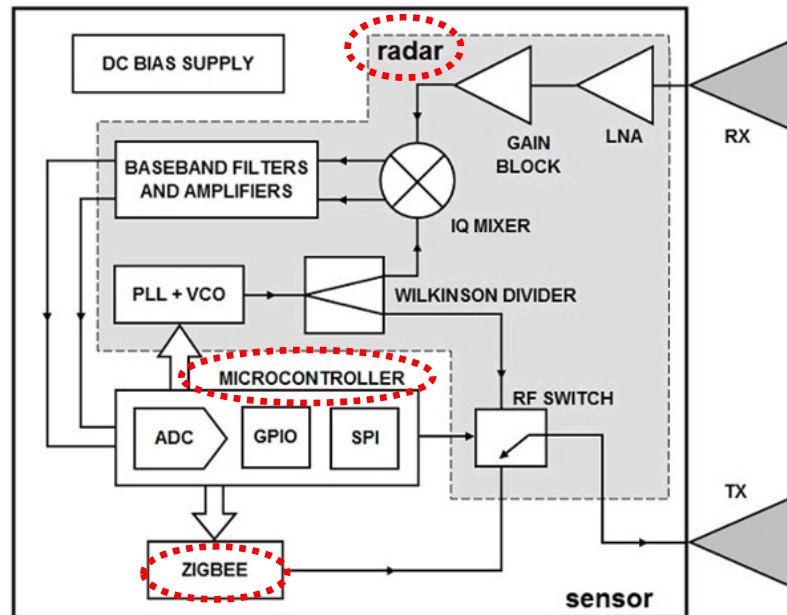
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- **Conclusions**

Radar WSN



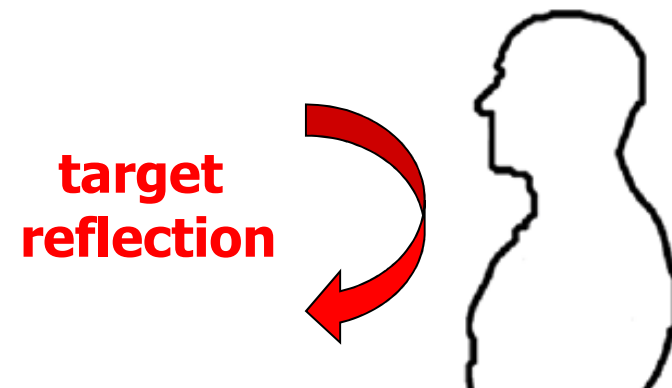
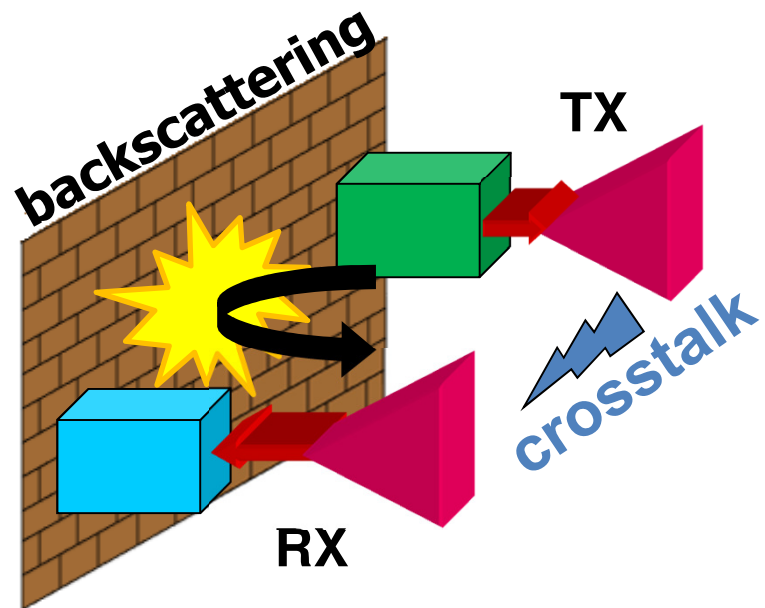
Radar Sensor



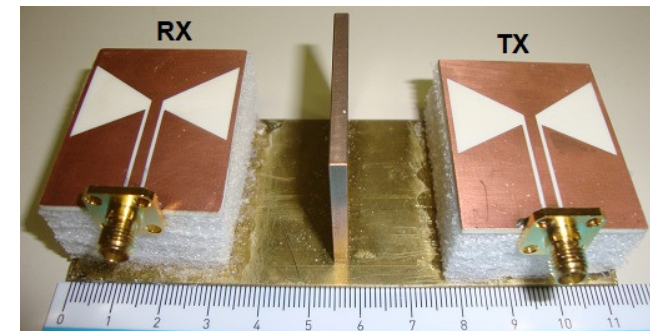
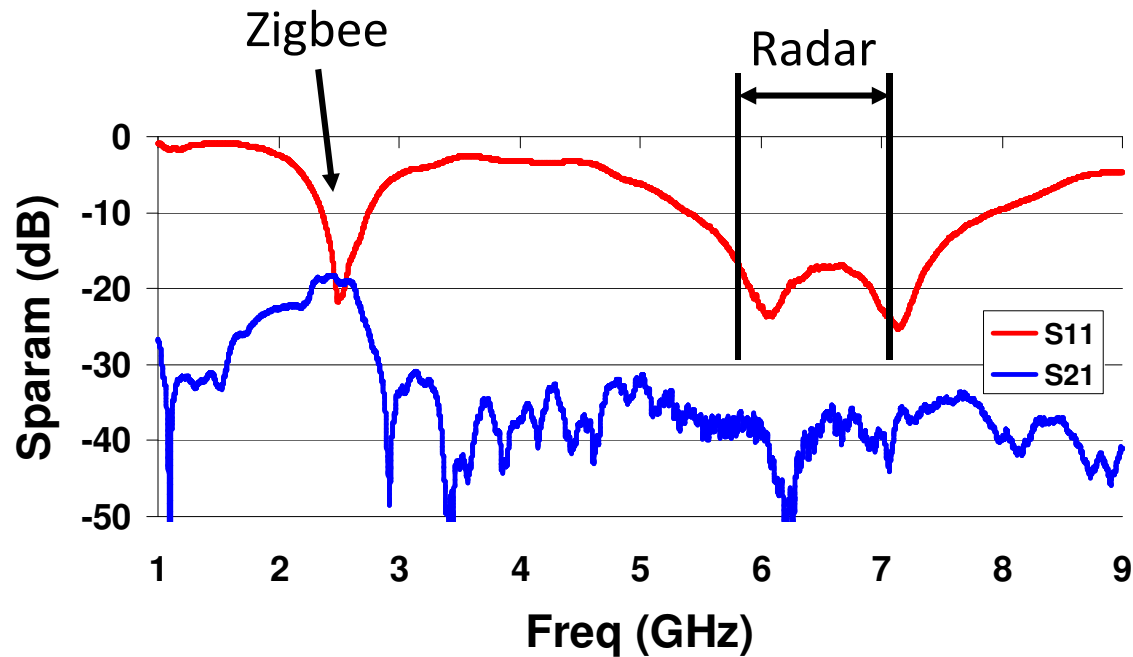
M. Mercuri, *et al.*, "Analysis of an indoor biomedical radar-based system for health monitoring," *IEEE Trans. Microw. Theory Techn.*, vol. 61, no. 5, pp. 2061-2068, May 2013.

Antenna Design

- In-door setting = sensor mounted to wall or ceiling
- Antenna design challenges
 - avoid backscattering & crosstalk
 - semi-spherical radiation pattern
 - wideband requirement



Antenna Design

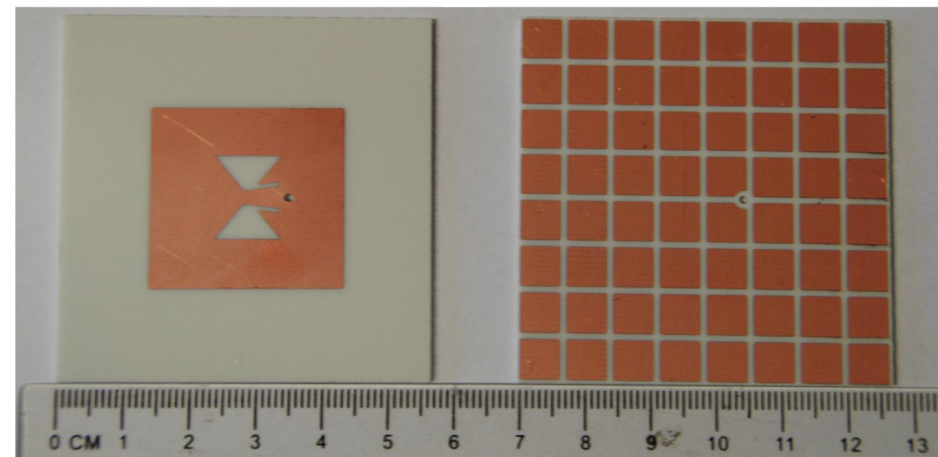
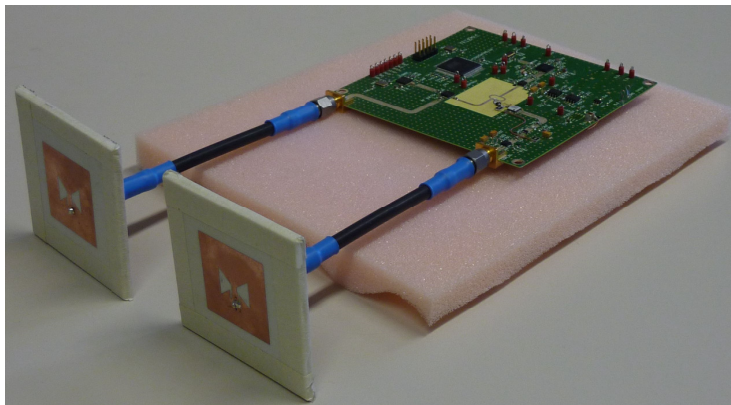
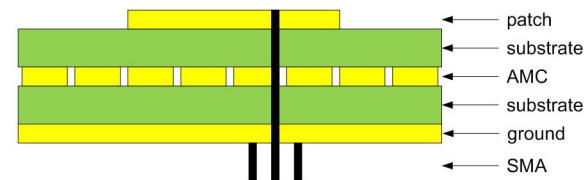


- **Ground Plane:** *backscattering*
- **Metal Wall:** *crosstalk (S_{21})*

AMC Based Antenna Design

Design based on **Artificial Magnetic Conductor (AMC)** layer

- smaller form factor
- no metal wall!



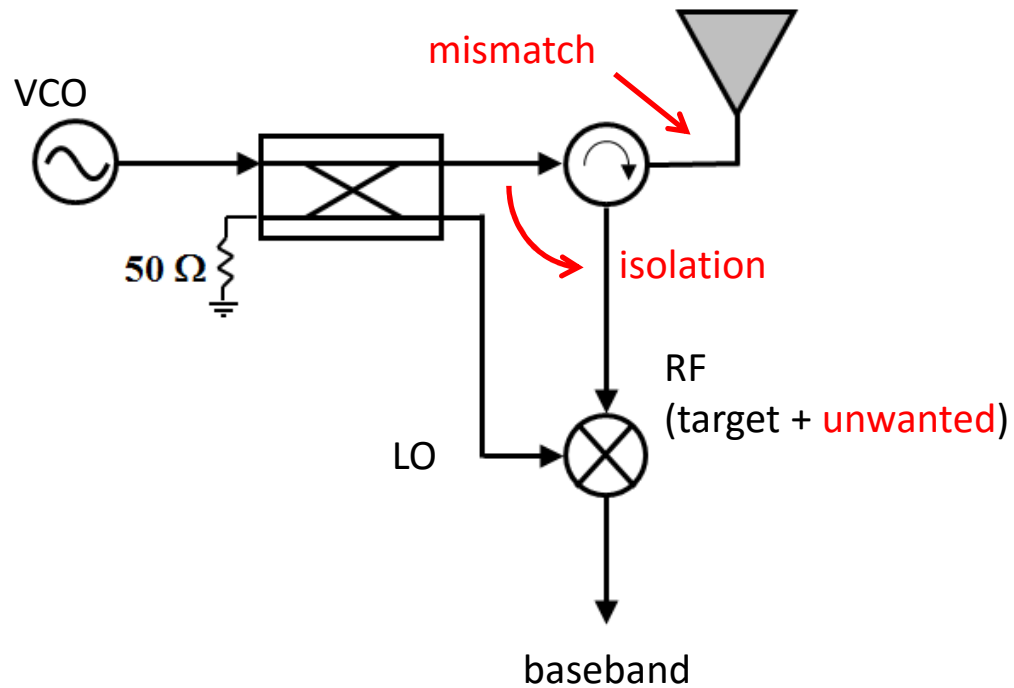


AMC Based Antenna Design

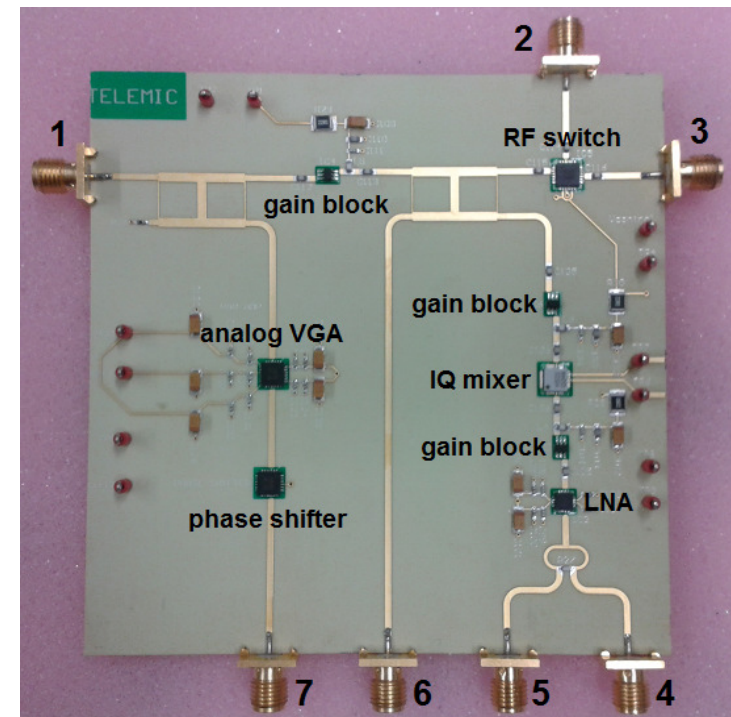
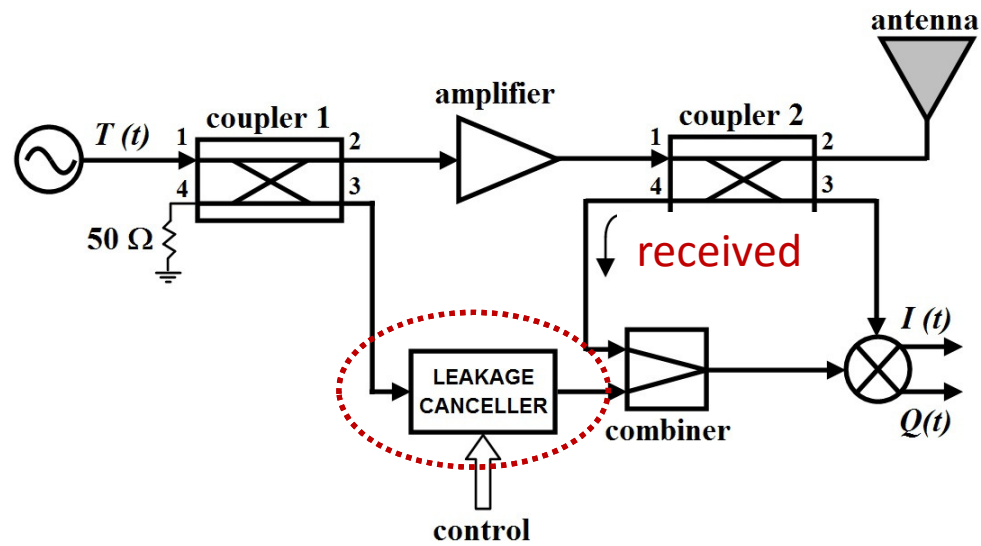
| | AMC Antenna | Reference Antenna |
|-------------------------|-------------|-------------------|
| Size (mm ³) | 56×56×3.12 | 42×36×32 |
| Low Freq. Band (GHz) | 2.395-2.485 | 2.22-2.48 |
| High Freq. Band (GHz) | 5.78-8.89 | 5.8-6.77 |
| Gain (dB) @ 2.45 GHz | 5.05 | 5.7 |
| Gain (dB) @ 6-7 GHz | >7.0 | >7.2 |
| FBR (dB) & 2.45 GHz | 15 | 0 |
| FBR (dB) & 6-7 GHz | >11 | >7.5 |
| Cross coupling (dB) | <-25 | <-25 (with wall) |

FBR = Front-to-Back Ratio

Monostatic Radar Architecture



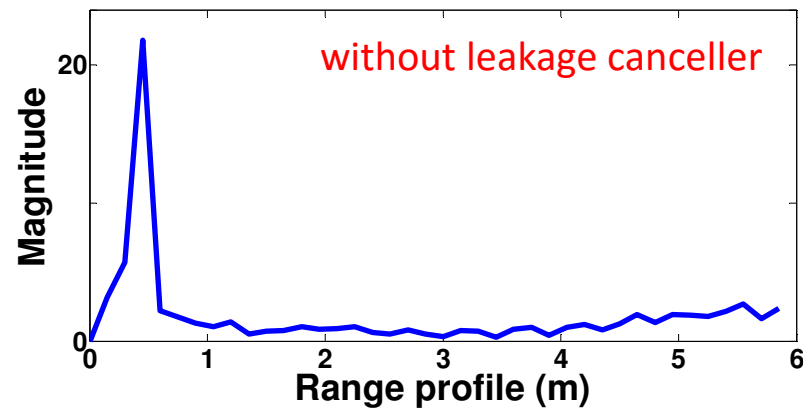
Monostatic Radar Architecture



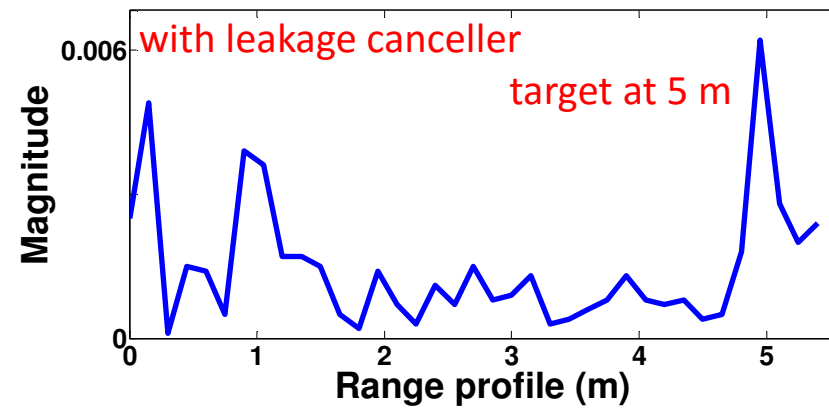
Monostatic Radar Architecture



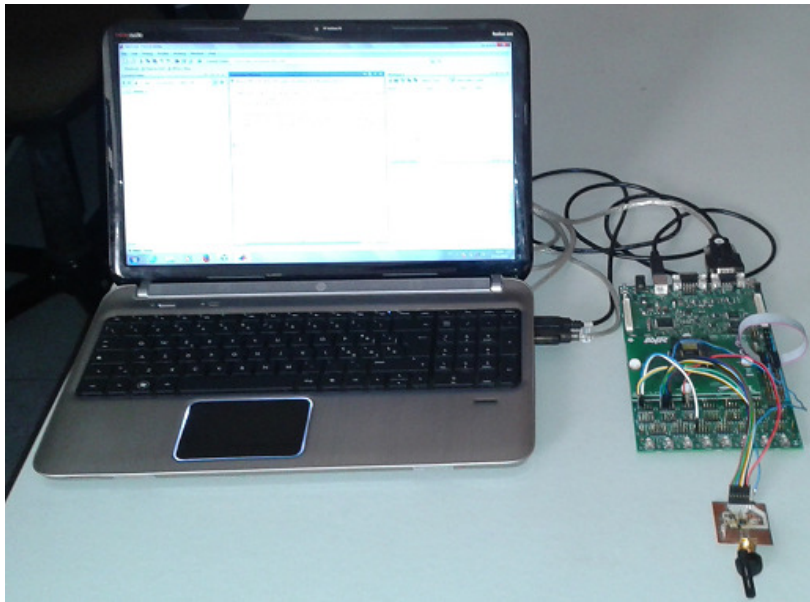
UNWANTED LEAKAGE



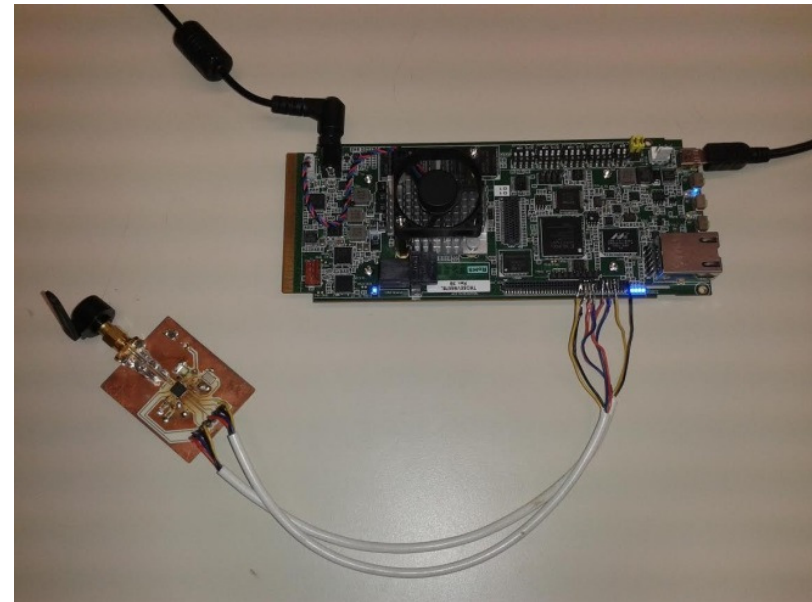
TARGET DETECTED



Base Station



Microcontroller-based



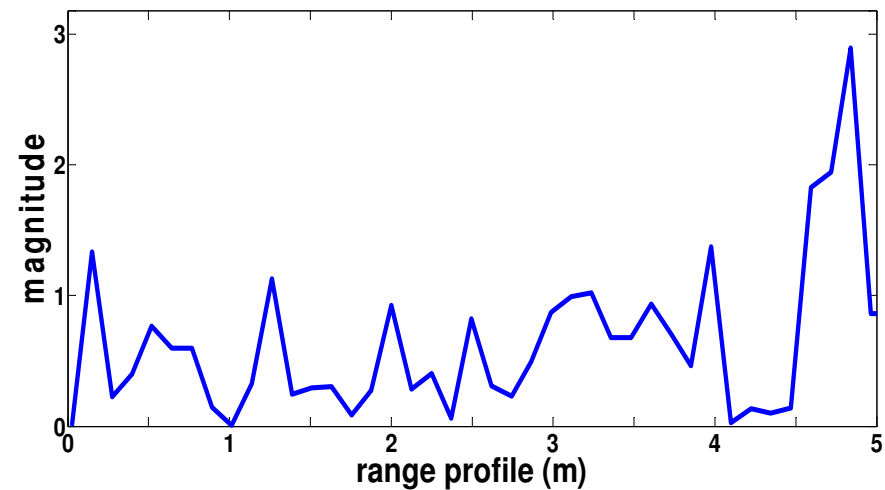
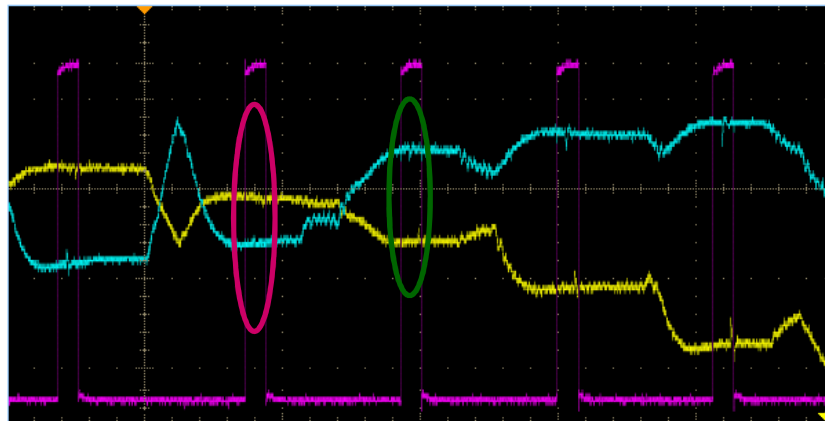
DSP-based

Data Processing: Localisation

- IFFT on SFCW baseband signals \rightarrow absolute distances

| f_0 | $f_0 + \Delta f$ | $f_0 + 2\Delta f$ | ... | $f_0 + (N-1)\Delta f$ |
|-------|------------------|-------------------|-----|-----------------------|
| C1 | C1 | C2 | ... | C1N |

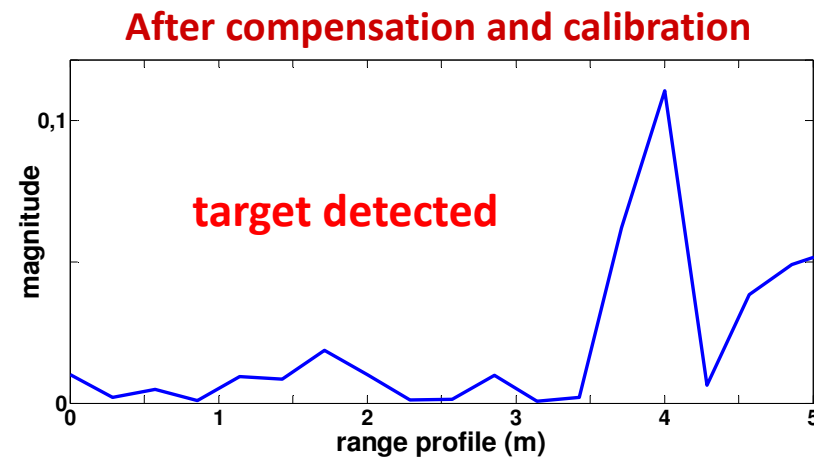
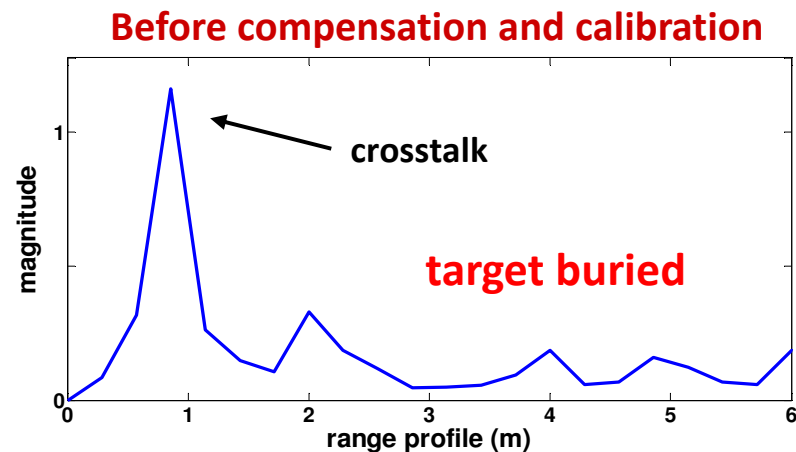
IFFT



Data Processing: Localisation

- **Compensation** → remove 'static' reflections (e.g., furniture, crosstalk)
- **Calibration** → places the target in the right position

Example: Target at 4 m



Reducing backscattering and crosstalk is fundamental!

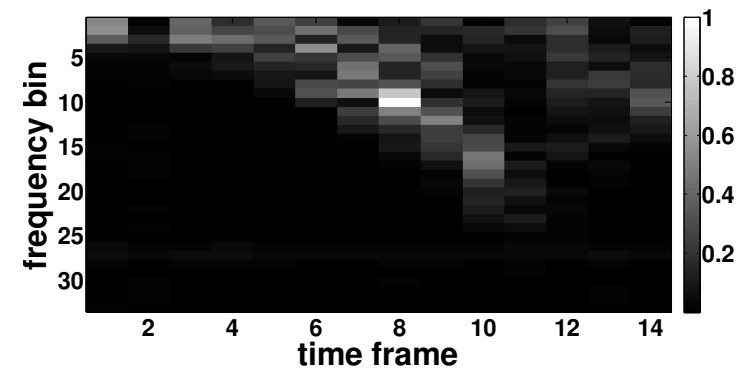
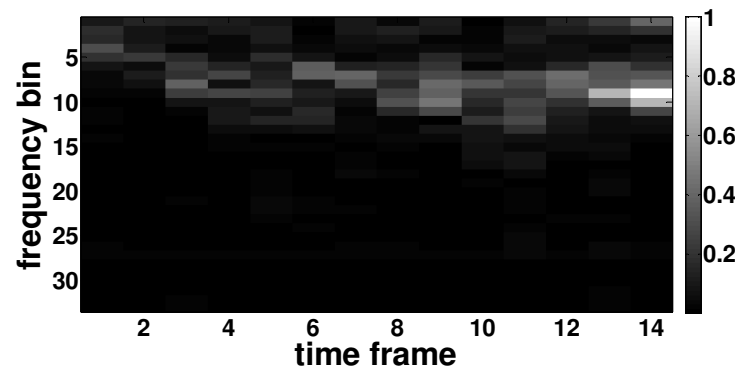
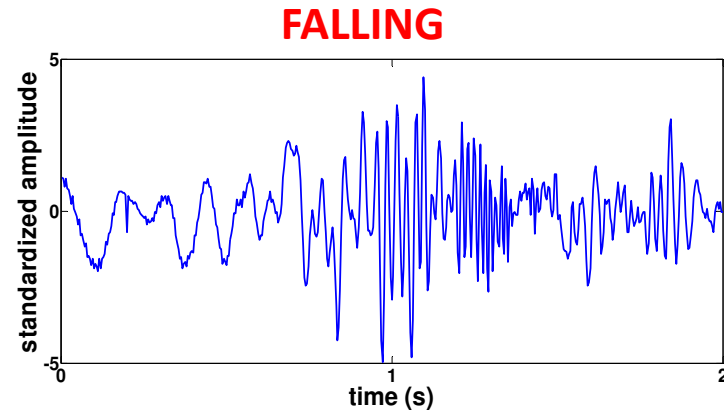
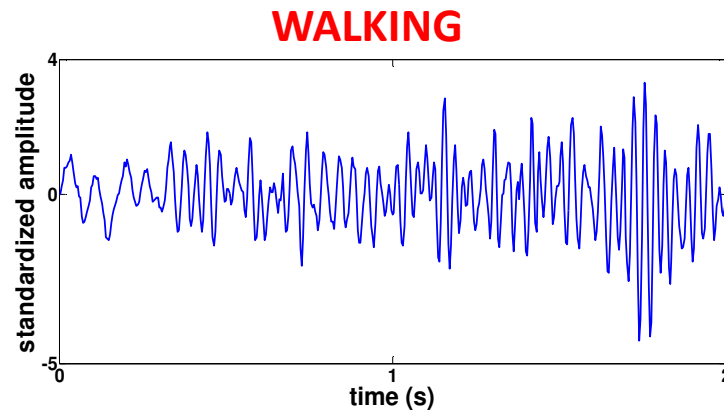


Data Processing: Localisation

| Distance | Anechoic Chamber | | | Real Room | | |
|----------|------------------|-----------|---------|-----------|-----------|---------|
| | % Person1 | % Person2 | % Metal | % Person1 | % Person2 | % Metal |
| 1 m | 100 | 100 | 100 | 100 | 100 | 100 |
| 2 m | 100 | 100 | 100 | 100 | 100 | 100 |
| 3 m | 93.3 | 96.7 | 100 | 90 | 86.7 | 100 |
| 4 m | 93.3 | 93.3 | 100 | 90 | 83.3 | 100 |
| 5 m | 86.67 | 90 | 100 | 76.7 | 73.3 | 100 |

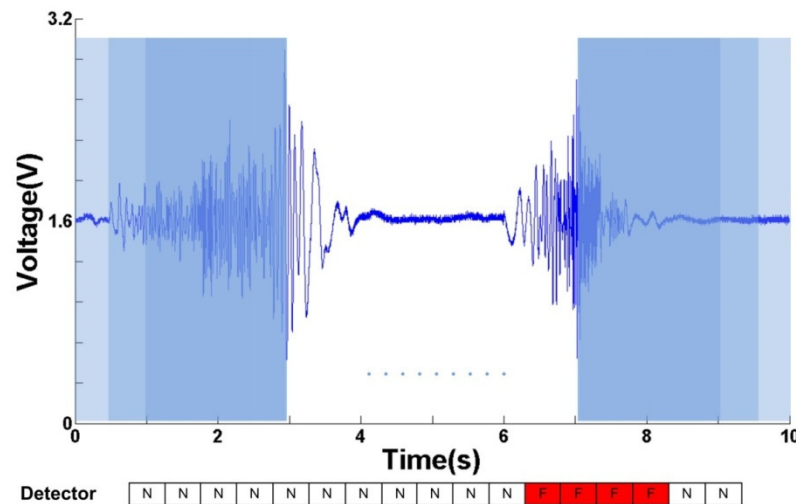
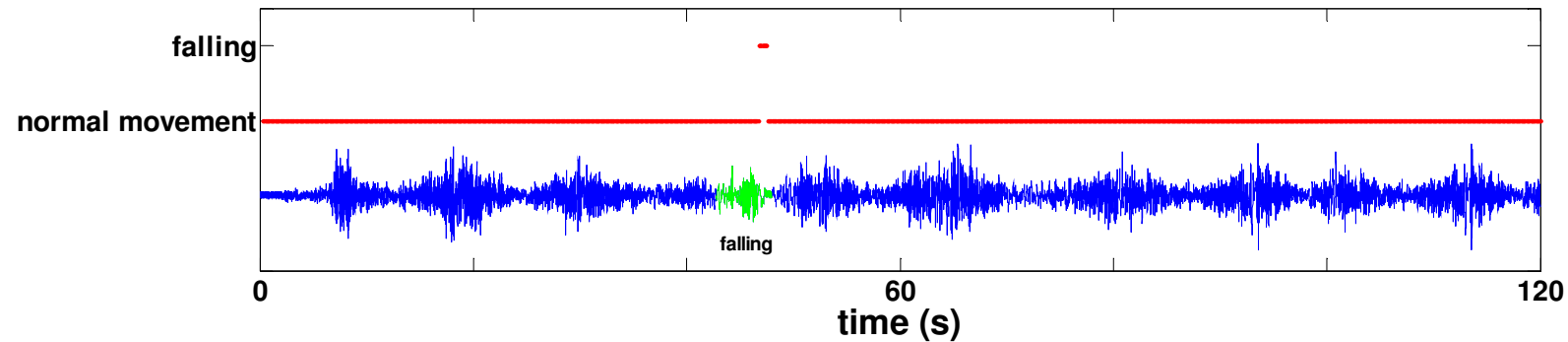
➤ 30 range profile measurements for each distance and for each target

Data Processing: **Fall Detection**



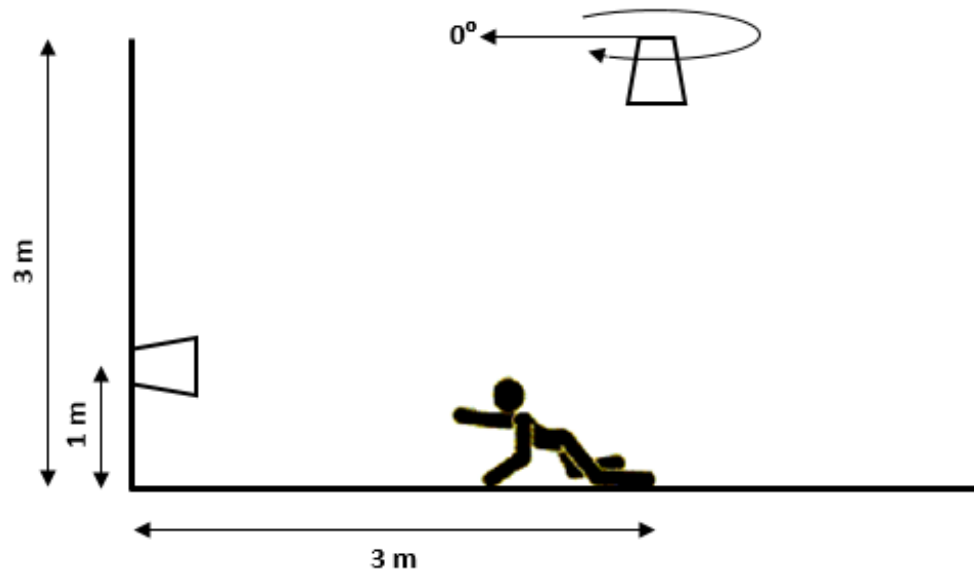
Classification approach: LS-SVM-GA

Real-Time Fall Detection



- **Sliding window** approach = Segmentation
- **Real-time** operation
 - ~316 ms maximum delay

Fall Detection: Sensor Positioning

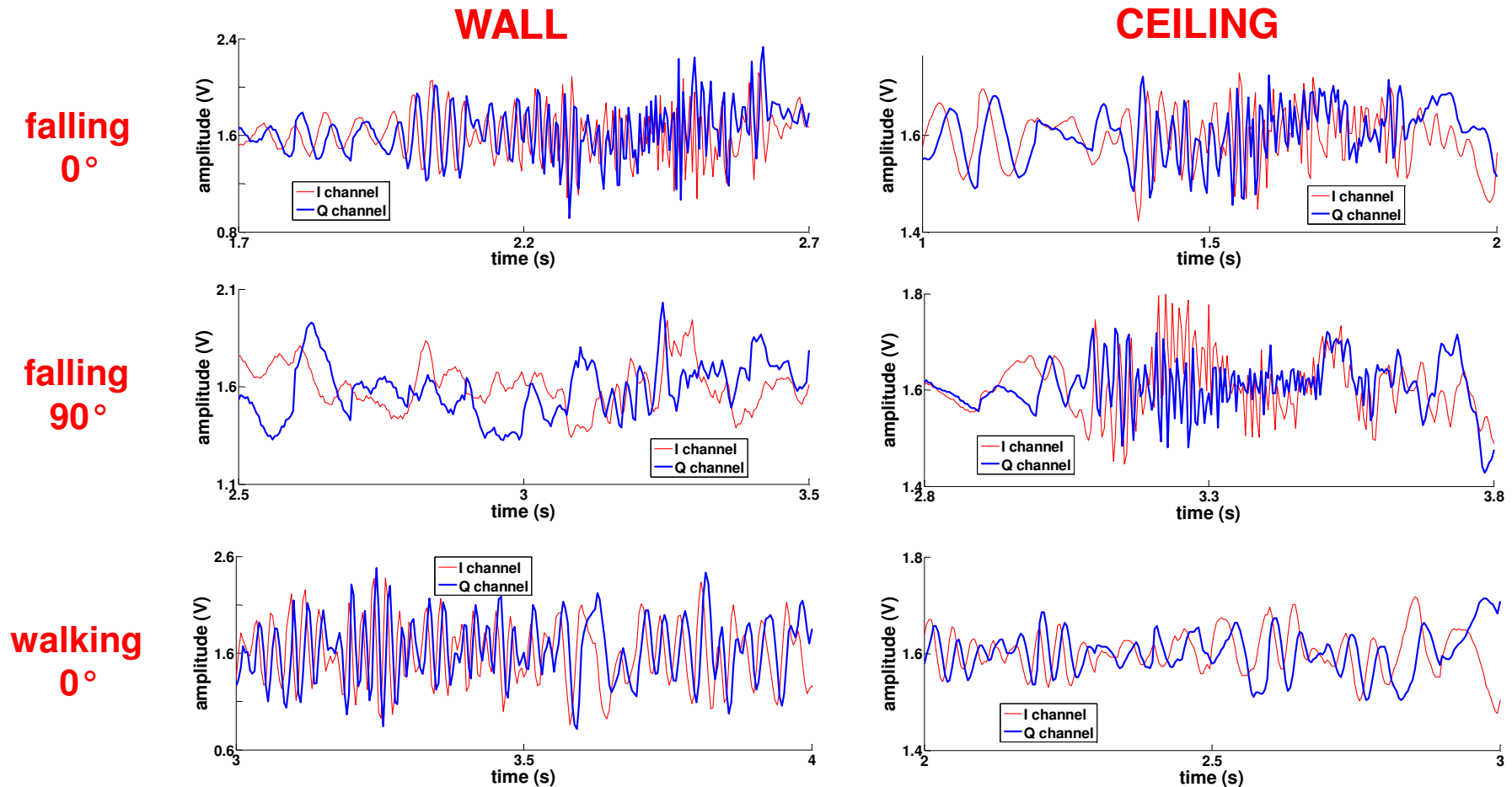


SPEED MEASUREMENTS:

- Sensor fixed to the **wall** or **ceiling**
- Falls over **different orientations**
- **3 subjects**



Fall Detection: Sensor Positioning



- Falls have an important vertical motion component
- Doppler effect limitation



Fall Detection: Sensor Positioning

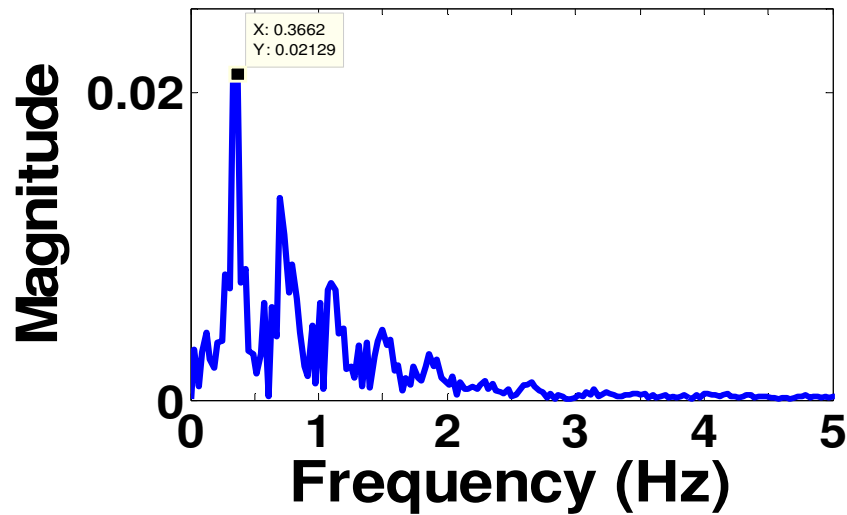
| Angle (°) | CEILING | | | WALL | | |
|----------------|-----------|-----------|-----------|-----------|-----------|-----------|
| | Subject 1 | Subject 2 | Subject 3 | Subject 1 | Subject 2 | Subject 3 |
| 0 | 3 | 3 | 3 | 3 | 3 | 3 |
| 30 | 3 | 3 | 3 | 3 | 3 | 3 |
| 60 | 3 | 3 | 3 | 0 | 0 | 0 |
| 90 | 3 | 3 | 3 | 0 | 0 | 0 |
| 120 | 3 | 3 | 3 | 0 | 0 | 0 |
| 150 | 3 | 3 | 3 | 3 | 3 | 3 |
| 180 | 3 | 3 | 3 | 3 | 3 | 3 |
| 210 | 3 | 3 | 3 | 3 | 3 | 3 |
| 240 | 3 | 3 | 3 | 0 | 0 | 0 |
| 270 | 3 | 3 | 3 | 0 | 0 | 0 |
| 300 | 3 | 3 | 3 | 0 | 0 | 0 |
| 330 | 3 | 3 | 3 | 3 | 3 | 3 |

– 3 mimicked frontal falls per target/position

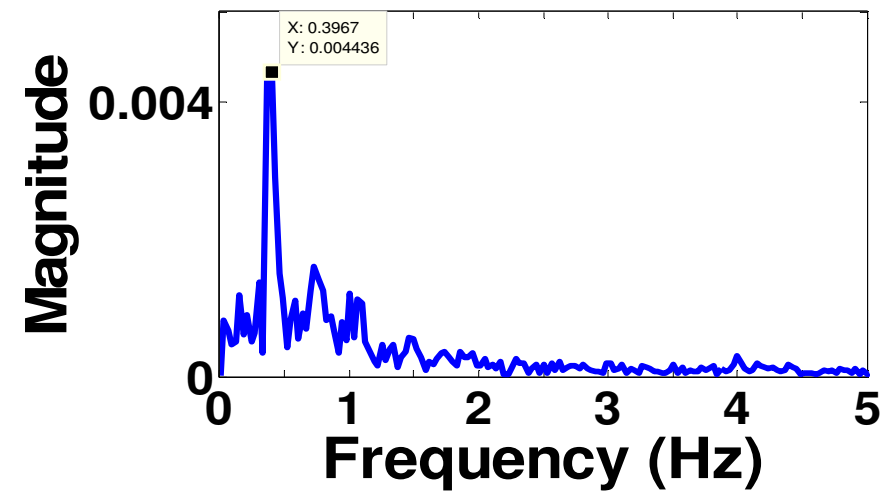
➤ Radar to the ceiling → to overcome Doppler effect limitation

Sensor Positioning: **Breathing**

Wall (Sensor 4 - frontal)



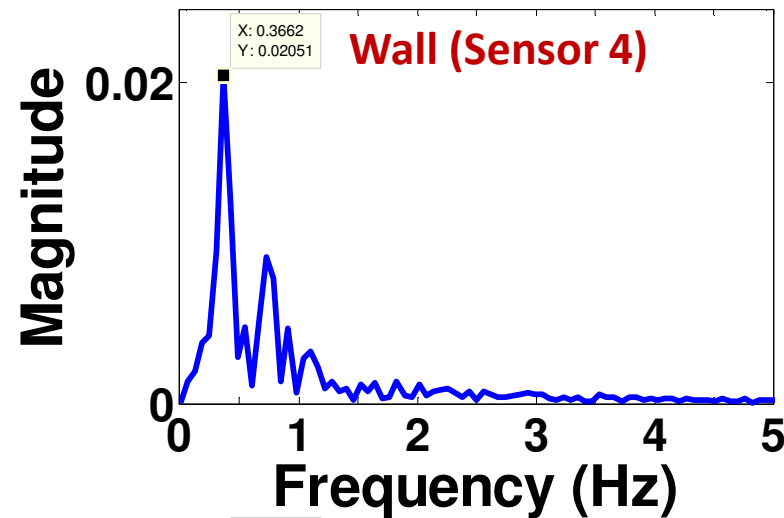
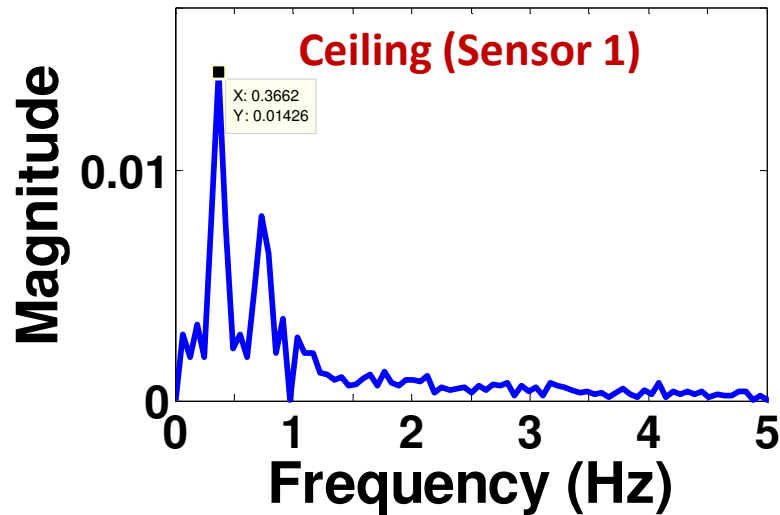
Wall (Sensor 3 - lateral)



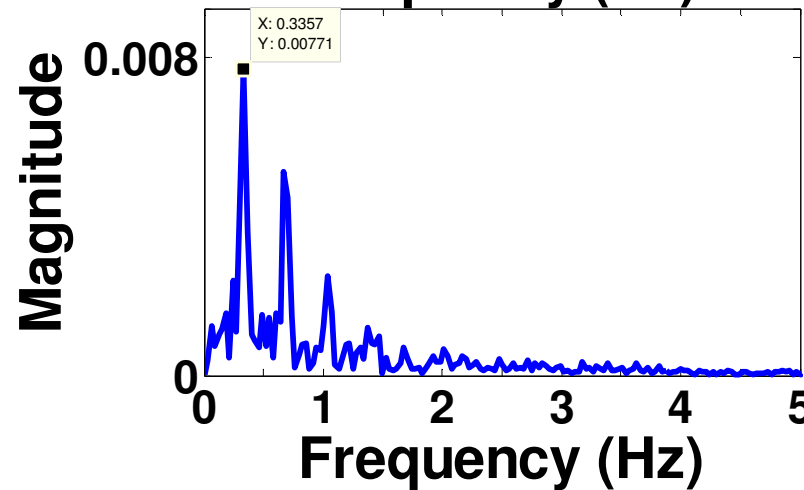
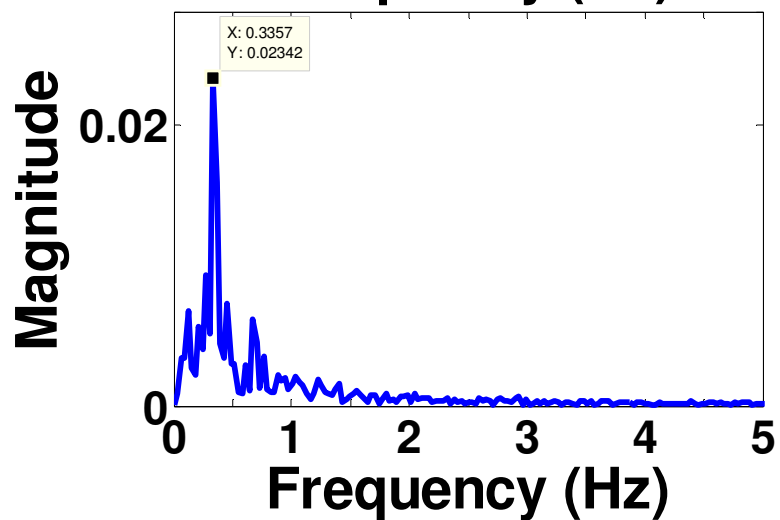
Person Sitting on a Chair



Sensor Positioning: Breathing



Prone

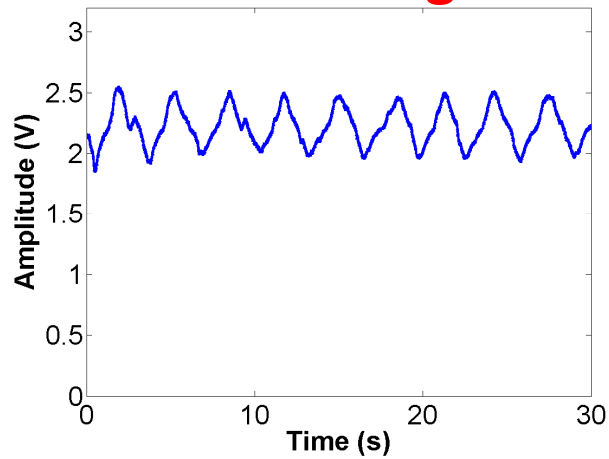


Supine

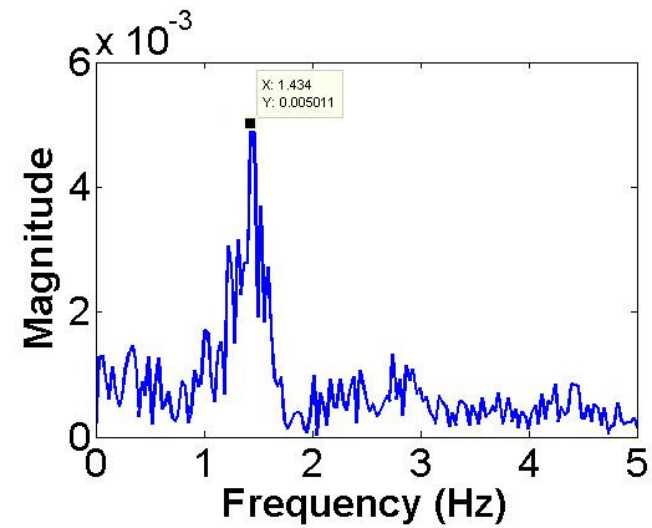
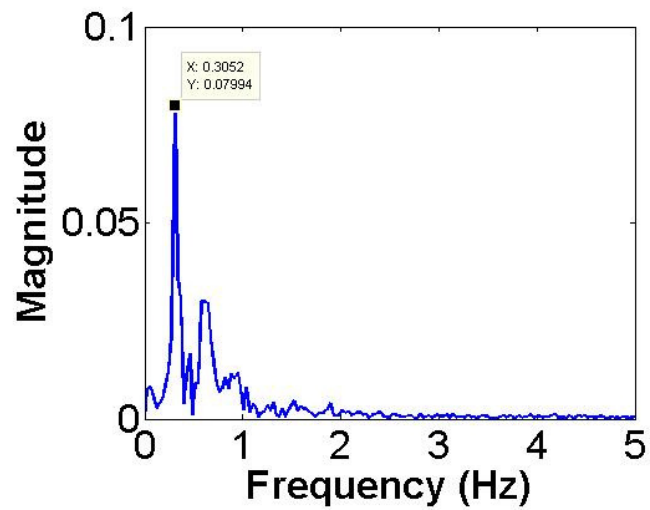
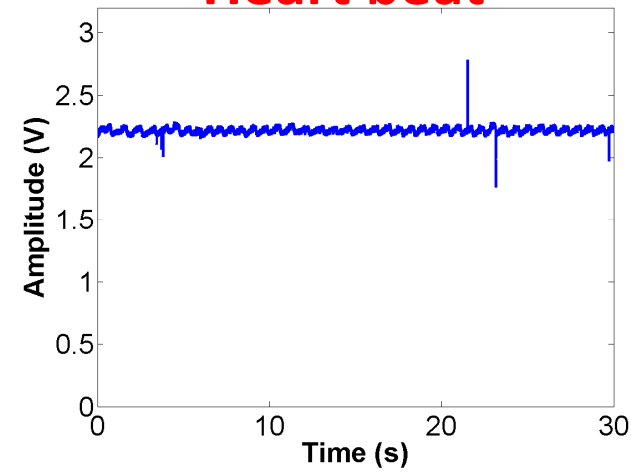
→ Clear benefit of having radar sensor network!

Vital Signs Monitoring

Breathing



Heart beat



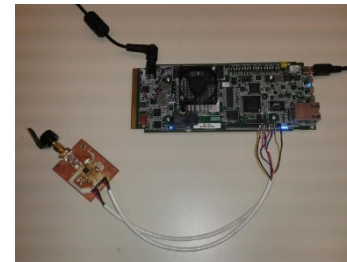


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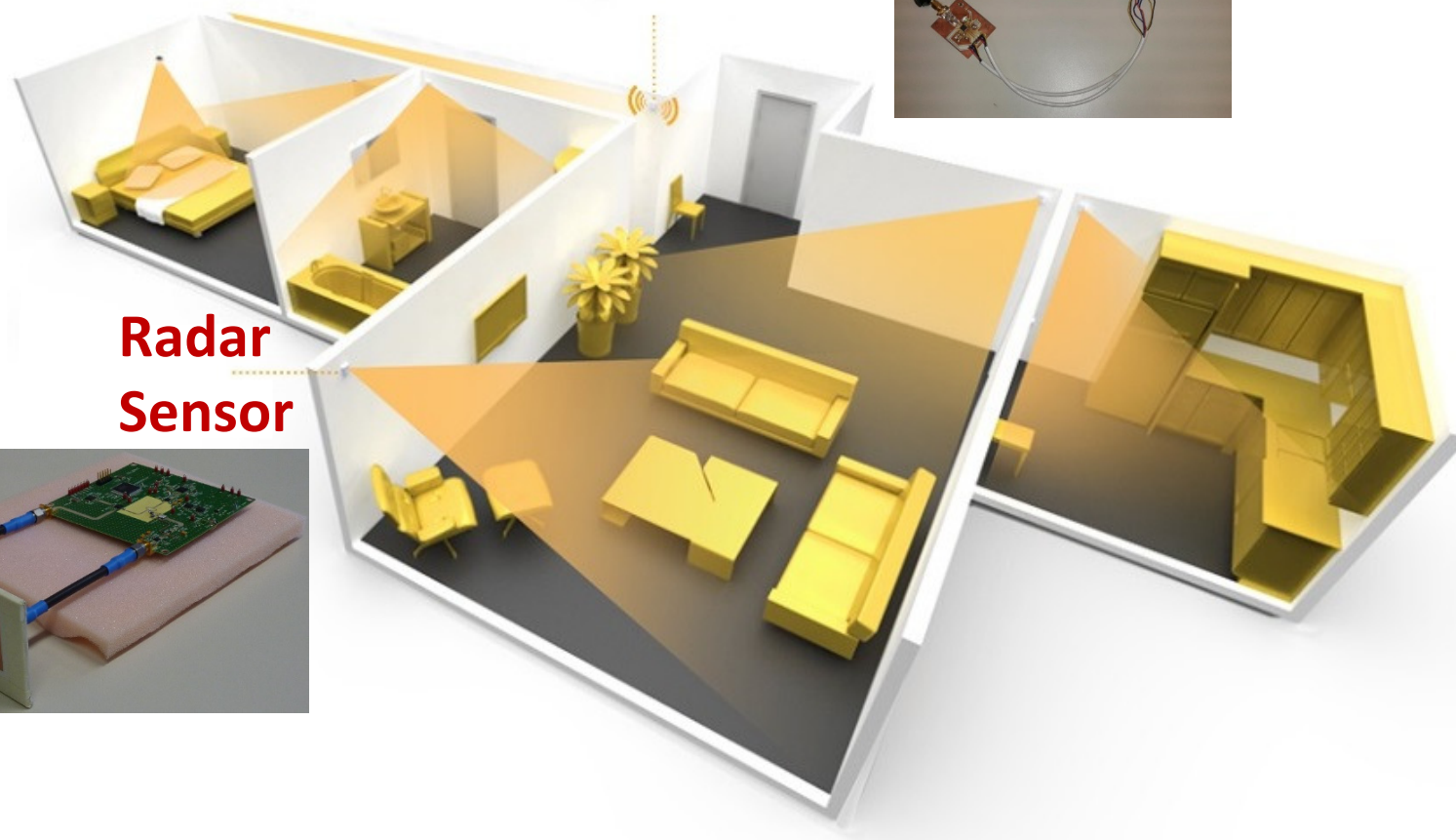
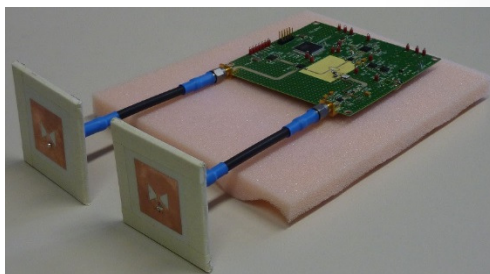
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Radar WSN

Base Station



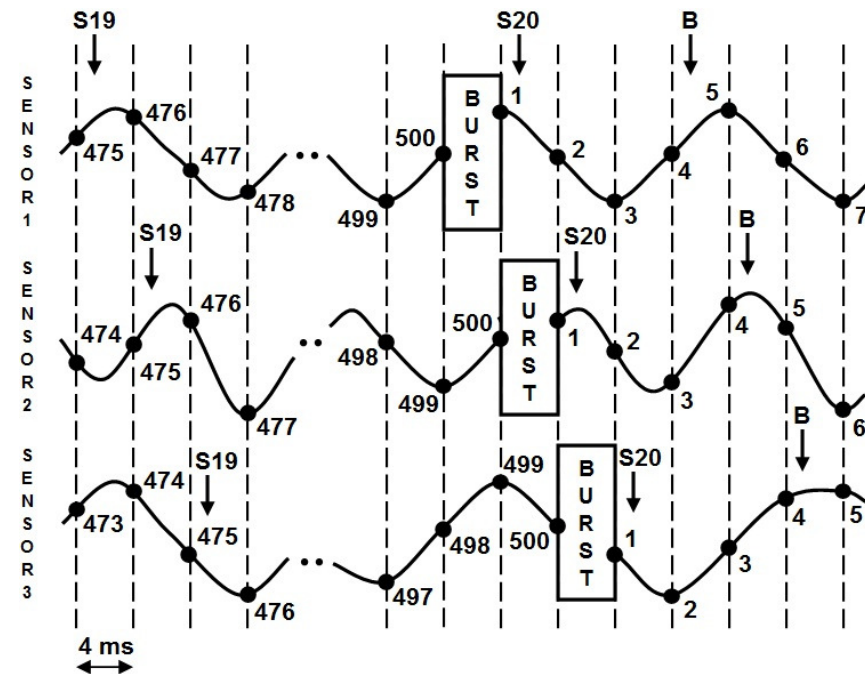
**Radar
Sensor**



Wireless Radar Sensor Network

- Challenges: synchronization & avoiding interference

- Radar operation
 - Speed: **FDM** among radar sensors
 - Localisation: **TDM**
 - one sensor at a time
- Wireless communications
 - **TDM**: Zigbee and radar sensing
 - **TDM**: 4 ms delay among sensors

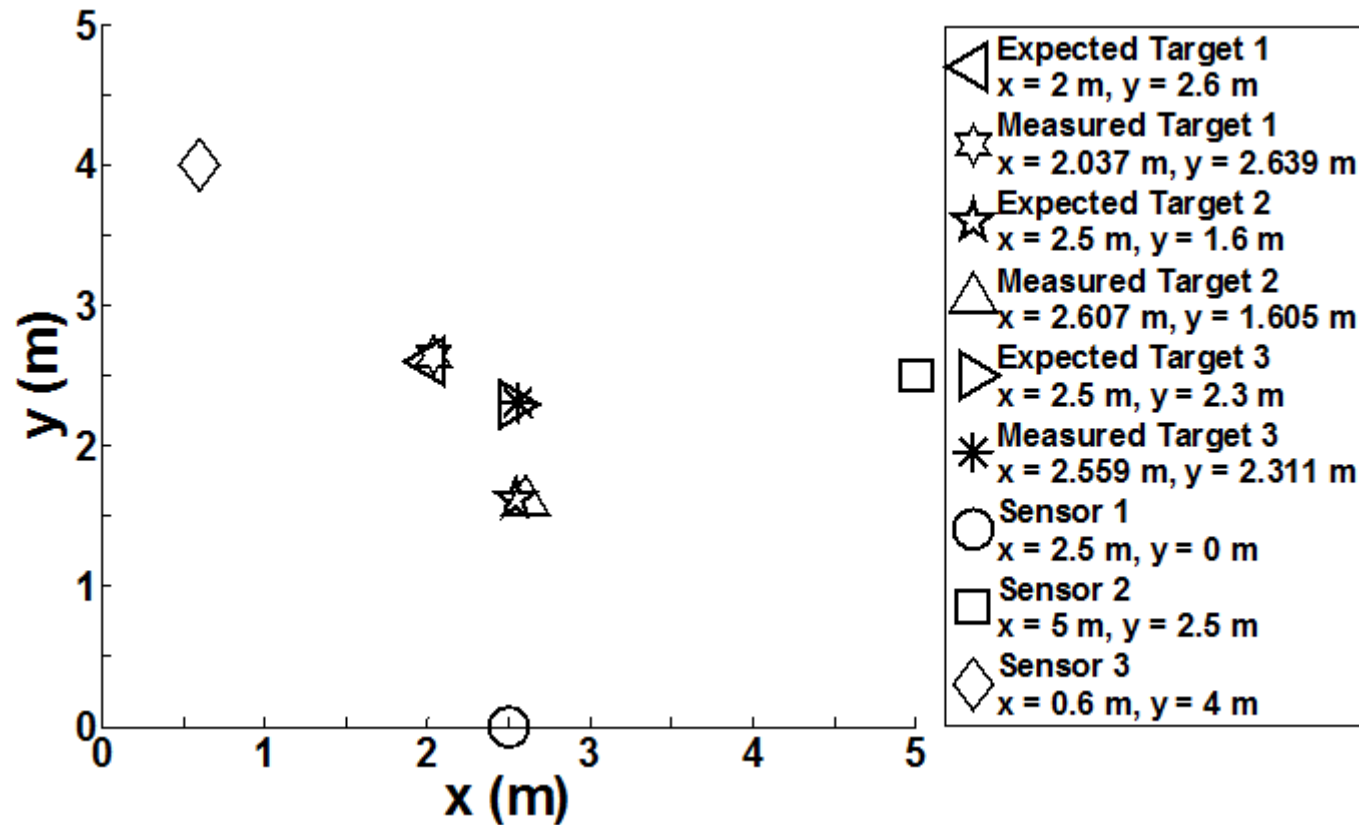


→ THE SENSORS VIRTUALLY OPERATE AT THE SAME TIME!!!

Experimental Setup

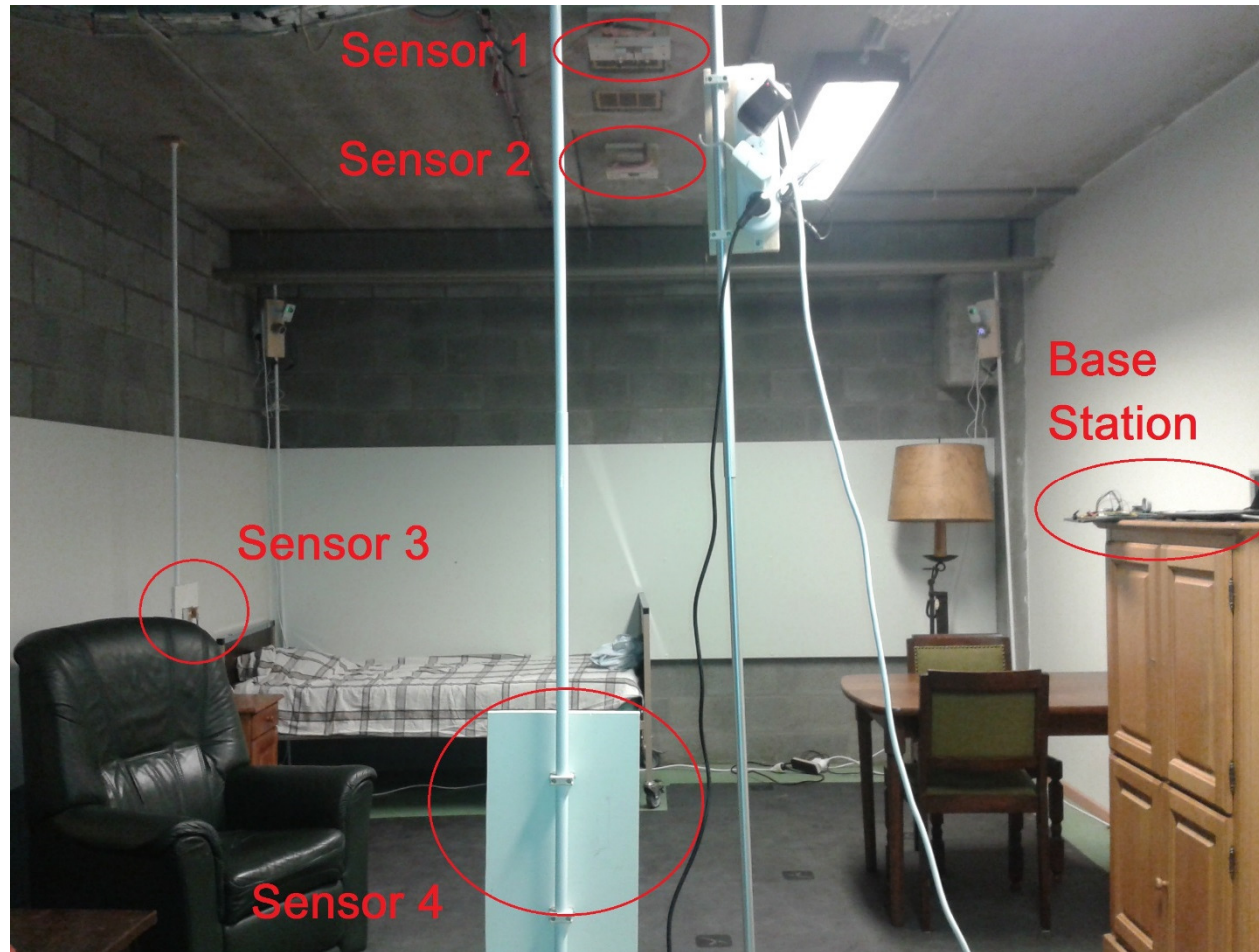


Localisation

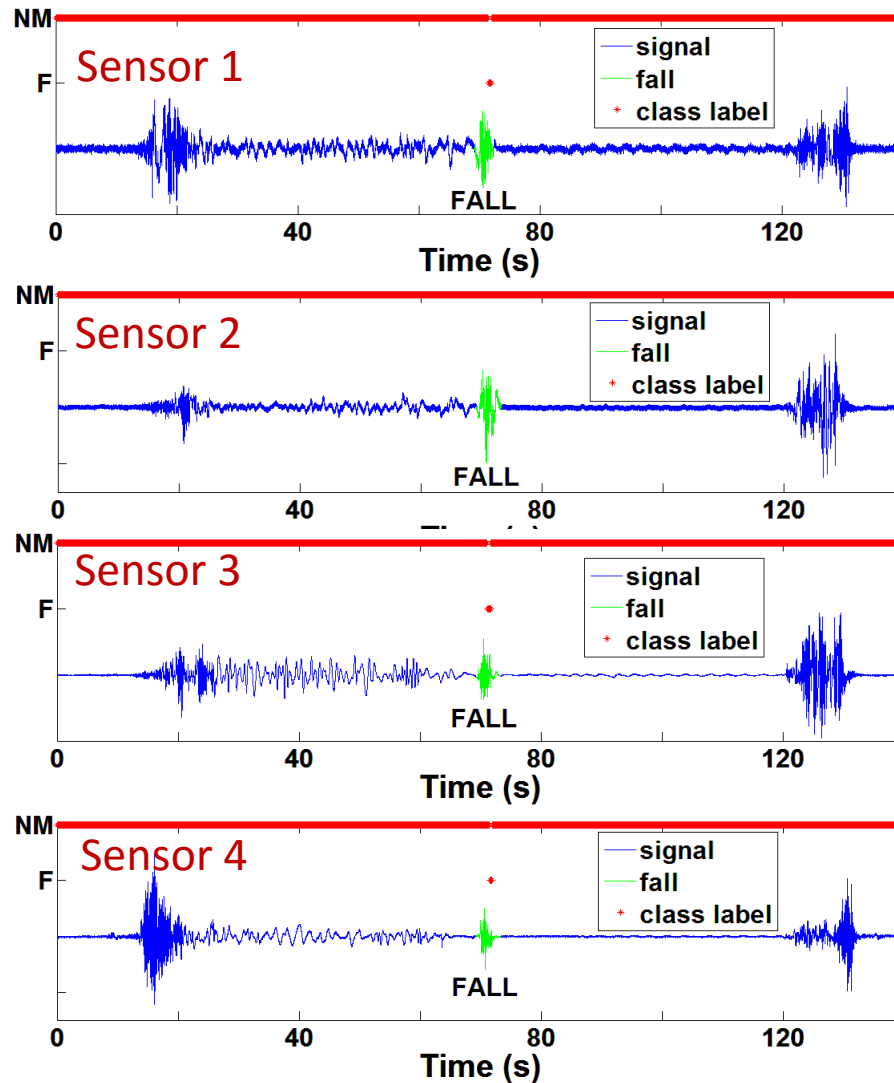


→ Errors within the radar resolution of 15 cm!

Experimental Setup



Experimental Results



Fall Detection

- Fall is not detected by Sensor 2
- Multiple sensors expand coverage range and improve detection reliability!



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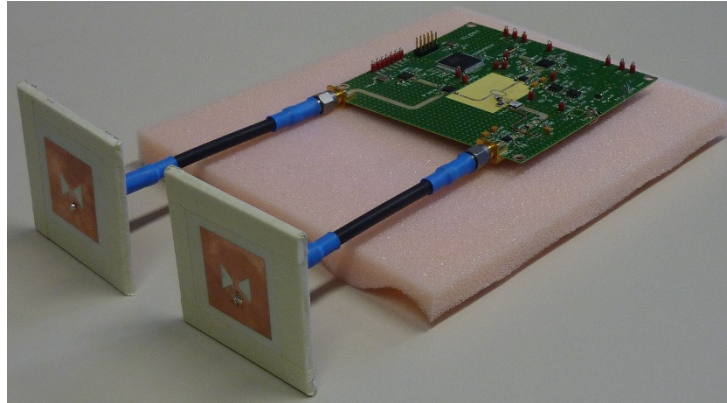
Smart Homes: Durability



Power needs

| Sensor | Power consumption (order of magnitude) |
|--------------------|--|
| Zigbee node | 40 mW |
| Temperature sensor | 0.5 mW |
| IR motion detector | 0.3 mW |
| Biomedical sensor | > 100 mW |

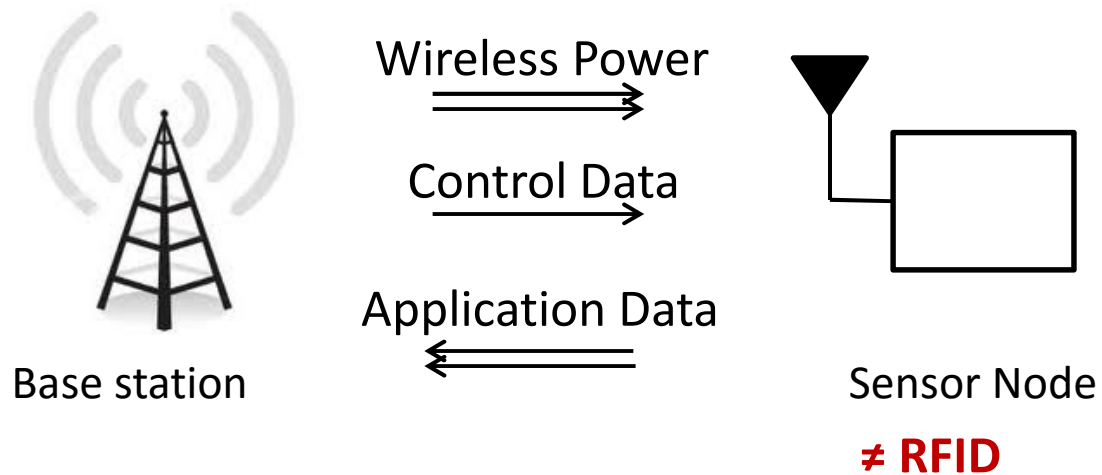
Smart Homes: Energy Needs



Power consumption radar sensor

- using off-the-shelf components:
 - wireless communications (Zigbee): 40 mW
 - radar sensing: >100 mW
 - microcontroller: 100 mW
- using dedicated chip design: 50 mW - 100 mW expected

Smart Homes: WPT?



Challenge: Single antenna @ Sensor Node

Regulations



Frequency Bands for Non-Specific Short Range Devices in Europe

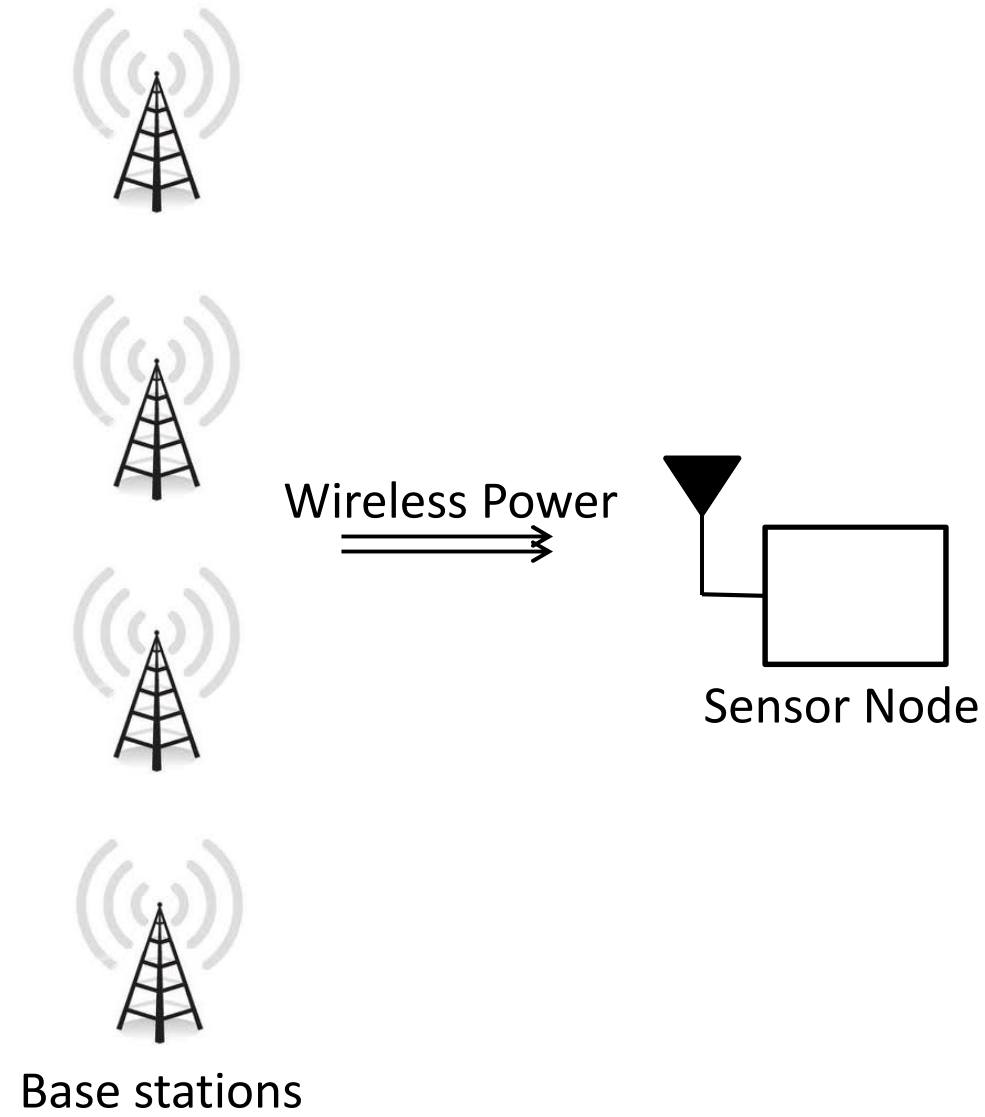
| Frequency Band | ERP | Duty Cycle | Channel Bandwidth | Remarks |
|---------------------|-----------|------------|-------------------|--|
| 433.05 – 434.79 MHz | +10 dBm | <10% | No limits | No audio and voice |
| 433.05 – 434.79 MHz | 0 dBm | No limits | No limits | ≤− 13 dBm/10 kHz, no audio and voice |
| 433.05 – 434.79 MHz | +10 dBm | No limits | <25 kHz | No audio and voice |
| 868 – 868.6 MHz | +14 dBm | < 1% | No limits | |
| 868.7 – 869.2 MHz | +14 dBm | < 0.1% | No limits | |
| 869.3 – 869.4 MHz | +10 dBm | No limits | < 25 kHz | Appropriate access protocol required |
| 869.4 – 869.65 MHz | +27 dBm | < 10% | < 25 kHz | Channels may be combined to one high speed channel |
| 869.7 -870 MHz | +7 dBm | No limits | No limits | |
| 2400 – 2483.5 MHz | +7.85 dBm | No limits | No limits | Transmit power limit is 10-dBm EIRP |

Ref: Electronic Communications Committee

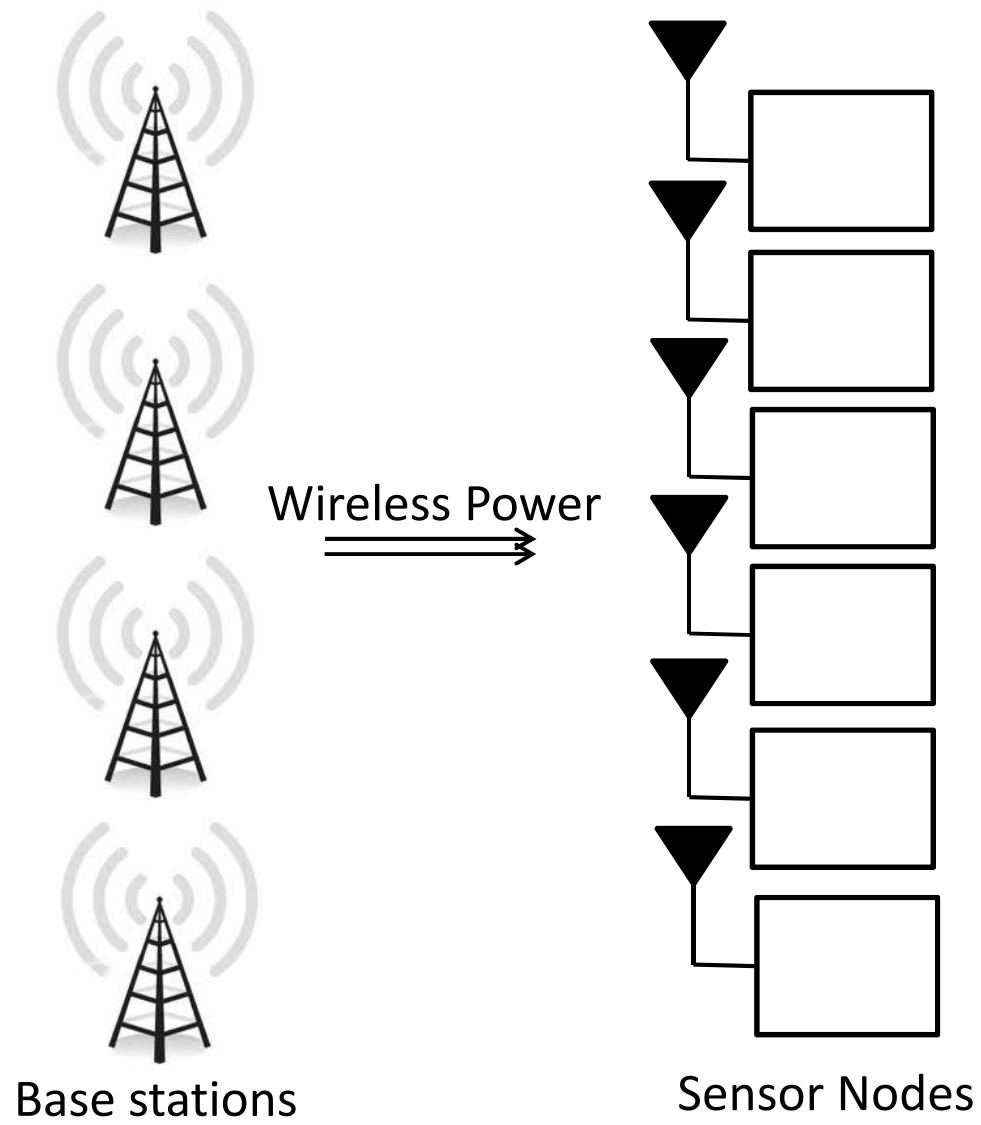


Single base station is not feasible

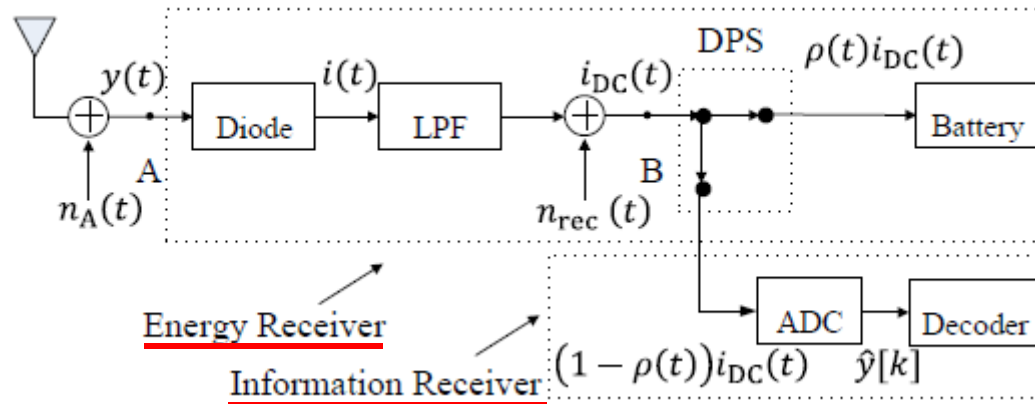
MISO WPT



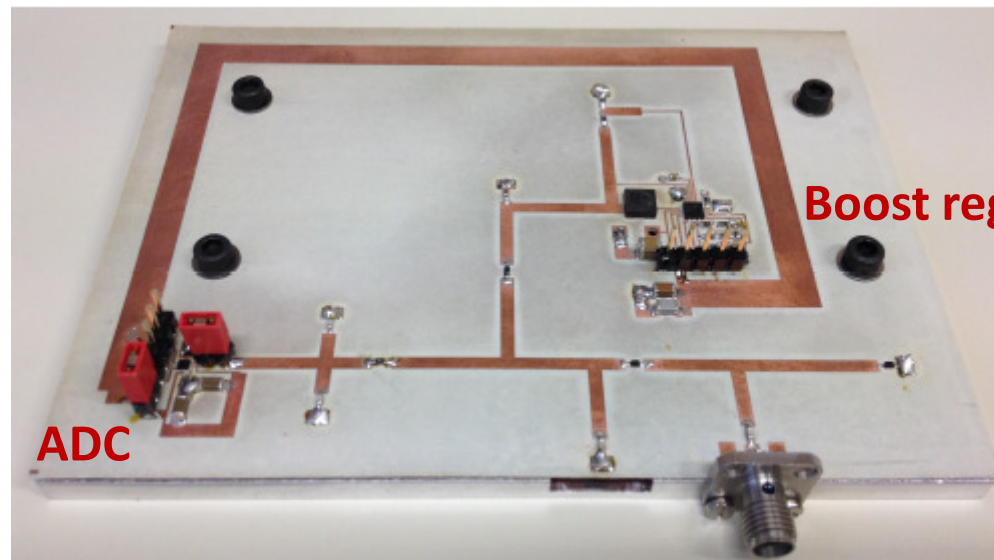
MIMO WPT



WPT & Data Receiver



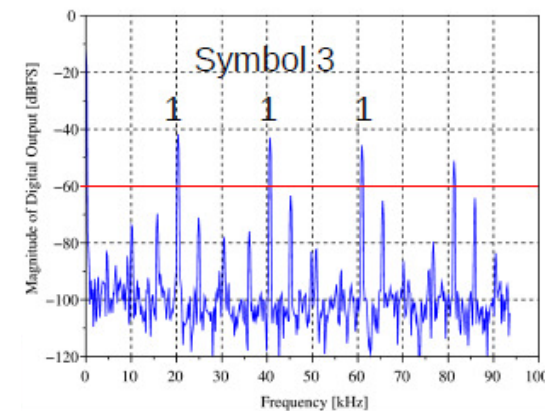
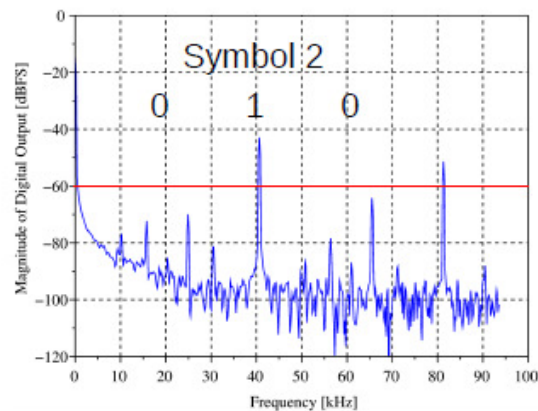
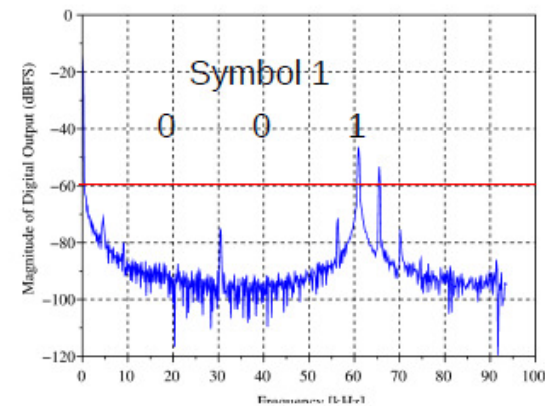
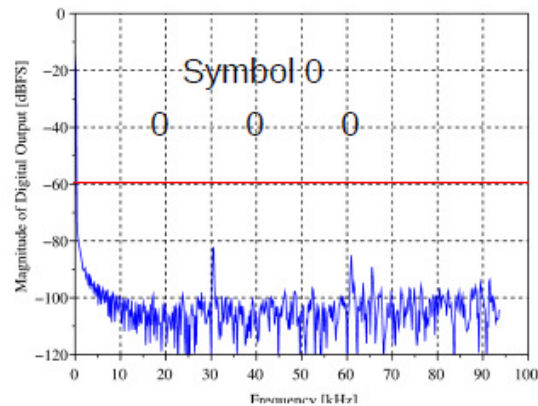
X. Zhou, *et al.*,
 IEEE Trans. Comm.,
 2013.



T.J. Lee, masterthesis,
 KU Leuven, 2016.

Experimental Results

- Modulation scheme such that received symbols are clear
- Received data signal is based on **baseband intermodulation products** of multisine RF excitation



T.J. Lee, masterthesis,
KU Leuven, 2016.

Conclusions

**Wireless radar sensor networks:
= viable technology for Smart Homes!**

